Adafruit SPI FRAM Breakout

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Overview



You're probably familiar with SRAM, DRAM, EEPROM and Flash but what about FRAM? FRAM is 'ferroelectric' RAM, which has some very interesting and useful properties. Unlike SRAM, FRAM does not lose the data when power is lost. In that sense it's a durable storage memory chip like Flash. However, it is much faster than Flash - and you don't have to deal with writing or erasing pages.



This particular FRAM chip has 64 Kbits (8 KBytes) of storage, interfaces using SPI, and can run at up to 20MHz SPI rates. Each byte can be read and written instantaneously (like SRAM) but will keep the memory for 95 years at room temperature. Each byte can be read/written 10,000,000,000,000 times so you don't have to worry too much about wear leveling.



With the best of SRAM and Flash combined, this chip can let you buffer fairly-high speed data without worrying about data-loss.

Pinouts



The FRAM chip is the little guy in the middle. On the bottom we have the power and interface pins

(http://adafru.it/dui)Power Pins:

- VCC this is the power pin. Since the chip uses 3-5VDC you should pick whatever the logic voltage you're using. For most Arduino's that's 5V.
- GND common ground for power and logic

SPI Logic pins:

All pins are 3-5V compliant and use whatever logic level is on VCC

• HOLD - this is a 'wait' pin for the SPI bus. When pulled low, it puts the SPI bus on

hold. This is different than the **CS** pin because it doesnt stop the current transaction. Its good if you want to talk to other SPI devices and stream data back and forth without stopping and starting transactions.

- SCK This is the SPI clock pin, its an input to the chip
- **MISO** this is the Master In Slave Out pin, for data sent from the FRAM to your processor
- **MOSI** this is the Master Out Slave In pin, for data sent from your processor to the FRAM
- **CS** this is the chip select pin, drop it low to start an SPI transaction. Its an input to the chip
- WP Write Protect pin. This is used to write protect the**status register only**! This pin does not directly affect write protection for the entire chip. Instead, it protects the block-protect register which is configured however you want (sometimes only half the FRAM is protected)

Assembly





Prepare the header strip:

Cut the strip to length if necessary. It will be easier to solder if you insert it into a breadboard - **long pins down**



Add the breakout board:

Place the breakout board over the pins so that the short pins poke through the breakout pads



And Solder!

Be sure to solder all pins for reliable electrical contact.

(For tips on soldering, be sure to check out our <u>Guide to Excellent</u> <u>Soldering</u> (http://adafru.it/aTk)).



You're done! Check your solder joints visually and continue onto the next steps

Wiring and Test



Arduino Wiring

Woops, the above has VCC and GND both connected to ground - Instead, connect VCC to the red power rail!

You can easily wire this breakout to any microcontroller, we'll be using an Arduino

- Connect Vcc to the power supply, 3V or 5V is fine. Use the same voltage that the microcontroller logic is based off of. For most Arduinos, that is 5V
- Connect **GND** to common power/data ground
- Connect the **SCK** pin to the SPI clock pin on your Arduino. We'll be using**Digital #13** which is also the hardware SPI pin on an Uno
- Connect the **MISO** pin to the SPI MISO pin on your Arduino. We'll be using**Digital** #12 which is also the hardware SPI pin on an Uno.
- Connect the **MOSI** pin to the SPI MOSI pin on your Arduino. We'll be using**Digital #11** which is also the hardware SPI pin on an Uno.
- Connect the CS pin to the SPI CS pin on your Arduino. We'll be using **Digital #10** but any pin can be used later

Download Adafruit_FRAM_SPI

To begin reading and writing data, you will need to<u>download Adafruit_FRAM_SPI from our</u> <u>github repository</u> (http://adafru.it/du5). You can do that by visiting the github repo and manually downloading or, easier, just click this button to download the zip <u>Download Adafruit_FRAM_SPI Library</u> http://adafru.it/du6 Rename the uncompressed folder **Adafruit_FRAM_SPI** and check that the

Adafruit_FRAM_SPI folder contains Adafruit_FRAM_SPI.cpp and Adafruit_FRAM_SPI.h

Place the **Adafruit_FRAM_SPI** library folder your **arduinosketchfolder**/libraries/ folder. You may need to create the**libraries** subfolder if its your first library. Restart the IDE.

We also have a great tutorial on Arduino library installation at: <u>http://learn.adafruit.com/adafruit-all-about-arduino-libraries-install-use</u> (http://adafru.it/aYM)

Load Demo

Open up File->Examples->Adafruit_FRAM_SPI->MB85RS64V and upload to your Arduino wired up to the sensor

🔊 bargraphdemo Arduino 1.0.5	
File Edit Sketch Tools Help	
New	Ctrl+N
Open	Ctrl+0
Sketchbook	Carlo b
Evampler	
Close	Ctrl+W
Save	Ctrl+S
Save As	Ctrl+Shift+S
Junioad	Ctrl+11
Upload Using Programmer	Ctrl+U Ctrl+Shift+U
opidad osing Programmer	
Page Setup	Ctrl+Shift+P
Print	Ctrl+P
Preferences	Ctrl+Comma
Quit	Ctrl+Q
<pre>uintl6_t a = analogRead(A0);</pre>	
a /= 100; Serial.println(a):	
for (uint8 t i=0; i < n	umpins; i++;

Thats it! Now open up the serial terminal window at 9600 speed to begin the test.

The test is fairly simple - It first verifies that the chip has been found. Then it reads the value written to location #0 in the memory, prints that out and write that value + 1 back to location #0. This acts like a restart-meter: every time the board is reset the value goes up one so you can keep track of how many times its been restarted.

Afterwards, the Arduino prints out the value in every location (all 8KB!)

S COM70	
	Send
Found SPI FRAM	*
Restarted 0 times	
0x0: 0x1 0x00 0x00 0x00 0x00 0x00 0x00 0	0 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0x20: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0x40: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0x60: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0x80: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0xA0: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0xC0: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0xE0: 0x00 0x00 0x00 0x00 0x00 0x00 0x00	x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00
0x100: 0x00 0x00 0x00 0x00 0x00 0x00 0x0	0 0000 0000 0000 0000 0000 0000 0000 0000
0x120: 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0	0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0
0x140: 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0	- 0 00x0 00x0 00x0 00x0 00x0 00x0 00x0
< III	•
Autoscroli	Newline 🗸 9600 baud 🗸

Library Reference

The library we have is simple and easy to use

Hardware vs Software SPI

You can create the FRAM object using software-SPI (each pin can be any I/O) with

Adafruit_FRAM_SPI fram = Adafruit_FRAM_SPI(FRAM_SCK, FRAM_MISO, FRAM_MOSI, FRAM_CS);

or use hardware SPI

Adafruit_FRAM_SPI fram = Adafruit_FRAM_SPI(FRAM_CS);

which means the other 3 pins are the hardware SPI defined pins for your chip. Check the

SPI Reference page for details on which pins are which for your Arduino! (http://adafru.it/d5h)

Hardware SPI is faster (the chip can handle up to 20MHz), but you have to use fixed pins. Software SPI is not as fast (maybe 1MHz max on an UNO), but you can switch pins around.

Begin

You can initialize the SPI interface and chip with begin()

fram.begin()

It will return true or false depending on whether a valid FRAM chip was found

Writing

Then to write a value, call

```
fram.writeEnable(true);
fram.write8(address, byte-value);
fram.writeEnable(false);
```

to write an 8-bit value to the address location Later on of course you can also read with

fram.read8(address);

which returns a byte reading. For writing, you must enable writing before you send data to the chip, its for safety! However you can write as much as you want between the **writeEnable** calls

Block Protection

We dont cover how to protect subsections of the FRAM chip. It's covered a bit more inside the Datasheet.

For advanced users, we have two functions to set/get the Status Register. IF you want to set the status register dont forget that **WP** must be logical high!

uint8_t getStatusRegister();
setStatusRegister(uint8_t value);

Downloads

Datasheets & Files

- <u>MB85RS64V Datasheet</u> (http://adafru.it/du7)
- Fritzing object in Adafruit Fritzing library (http://adafru.it/aP3)
- EagleCAD PCB files (http://adafru.it/q6a)

Schematics

Fabrication Print

