

# SANYO Semiconductors DATA SHEET

An ON Semiconductor Company

# LB1641 — Bidirectional Motor Driver

#### Overview

The LB1641 is a bidirectional motor driver IC. Since it has a 2-input logic circuit and performs the functions of bidirectional driving and braking, it is capable of direct driving 6V, 9V, 12V motors. The output voltage can be varied by using an external zener diode.

#### **Features**

- 2-input logic can be used to exercise control of bidirectional driving and braking.
- On-chip elements to absorb dash current of motor.
- Input interfaceable to MOS LSI.
- Output voltage variable by use of external zener diode.

### **Specifications**

#### **Maximum Ratings** at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> max		18	٧
Input voltage	V <sub>IN</sub>		-0.3 to V <sub>CC</sub>	٧
Output circuit	IOUT		±1.6	Α
Allowable power dissipation	Pd max		1.2	W
Operating temperature	Topr		-25 to +75	°C
Storage temperature	Tstg		-55 to +125	°C

#### **Recommended Operating Ranges** at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V <sub>CC</sub> 1		7 to 18	V
	V <sub>CC</sub> <sup>2</sup>		5 to 18	V

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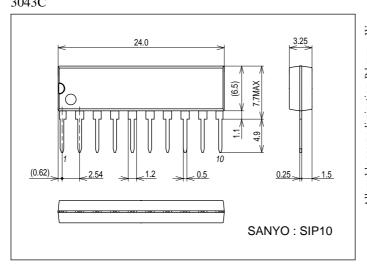
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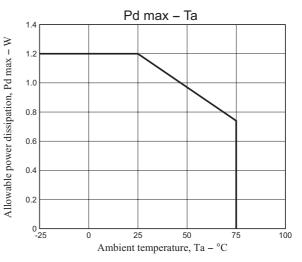
## **Electrical Characteristics** at Ta = 25°C, $V_{CC} = 12V$

Danamatan	0 11	0 - 111	Ratings			11.5
Parameter	Symbol	Conditions	min	typ	max	Unit
Input threshold voltage	Vth	R <sub>L</sub> = ∞	1.1	1.3	1.5	V
Minimum input on-state current	I <sub>IN</sub>	R <sub>L</sub> = ∞		10	15	μА
Output voltage	V <sub>O</sub>	$R_L = 60\Omega$ , $V_Z = 7.4V$	6.6	7.2	7.4	V
Output leakage current	l <sub>OL</sub>	Pins 5,6 GND, $R_L = \infty$		0.01	1.0	mA
Current drain	<sup>I</sup> CC	Pins 5,6 GND, $R_L = \infty$	3	6	10	mA
Saturation voltage (upper)	Vsat1	I <sub>OUT</sub> = 300mA		1.9	2.2	V
	Vsat1'	I <sub>OUT</sub> = 500mA		1.9	2.3	V
Saturation voltage (lower)	Vsat2	I <sub>OUT</sub> = 300mA		0.25	0.5	V
	Vsat2'	I <sub>OUT</sub> = 500mA		0.4	0.65	V

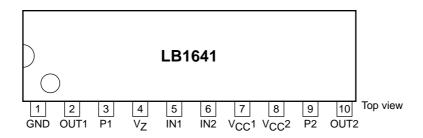
## **Package Dimensions**

unit : mm (typ) 3043C





## **Pin Assignment**

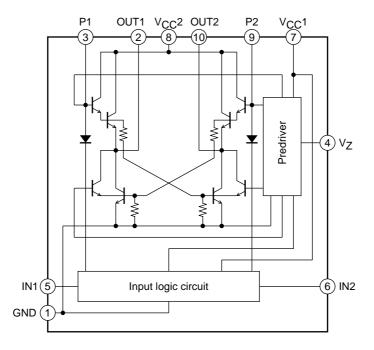


### **Truth Table**

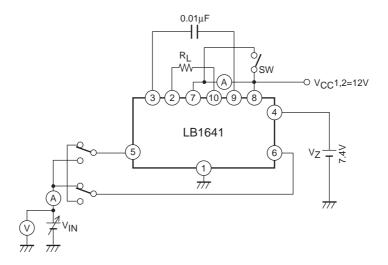
Inj	Input		tput	Operation
IN1	IN2	IN3	IN4	Operation
0	0	0	0	Braking
1	0	1	0	Forward (reverse) drive
0	1	0	1	Reverse (forward) drive
1	1	0	0	Braking

Input level 1 : 2.0V or greater 0 : 0.7V or less

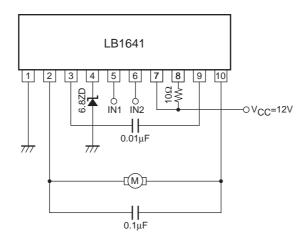
## **Block Diagram**

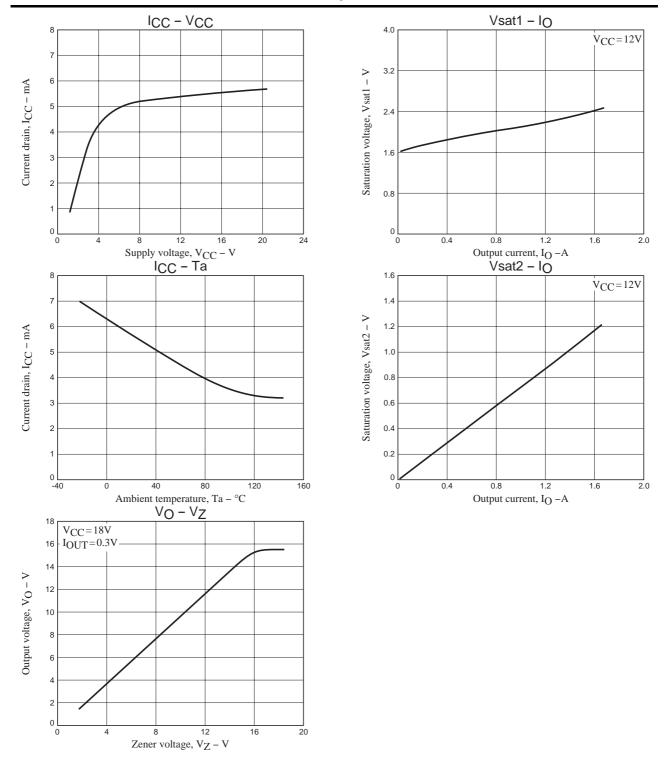


## **Test Circuit**



## Sample Application Circuit : 6V motor circuit





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