1.0 A Output Current, Dual Power Operational Amplifiers

The TCA0372 is a monolithic circuit intended for use as a power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. No deadband crossover distortion provides better performance for driving coils.

Features

- Output Current to 1.0 A
- Slew Rate of 1.3 V/µs
- Wide Bandwidth of 1.1 MHz
- Internal Thermal Shutdown
- Single or Split Supply Operation
- Excellent Gain and Phase Margins
- Common Mode Input Includes Ground
- Zero Deadband Crossover Distortion
- These Devices are Pb-Free, Halogen Free/BFR Free and are RoHS Compliant

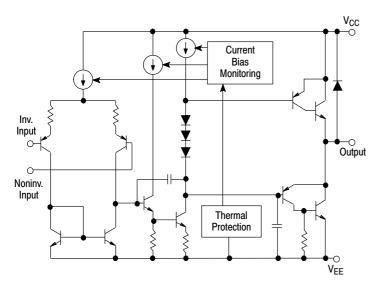


Figure 1. Representative Block Diagram



ON Semiconductor®

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PDIP-8 DP1 SUFFIX CASE 626



PDIP-16 DP2 SUFFIX CASE 648



SOIC-16W DW SUFFIX CASE 751G



SOEIAJ-16 DM2 SUFFIX CASE 966

ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 6 of this data sheet.

DEVICE MARKING INFORMATION

See general marking information in the device marking section on page 6 of this data sheet.

MAXIMUM RATINGS

Rating	Symbol	Value	Unit
Supply Voltage (from V _{CC} to V _{EE})	V _S	40	V
Input Differential Voltage Range	V _{IDR}	Note 1	V
Input Voltage Range	V_{IR}	Note 1	V
Junction Temperature (Note 2)	TJ	+150	°C
Operating Temperature Range	T _A	-40 to +125	°C
Storage Temperature Range	T _{stg}	-55 to +150	°C
DC Output Current	I _O	1.0	А
Peak Output Current (Nonrepetitive)	I _(max)	1.5	А
Thermal Resistance, Junction-to-Air Case 626 Case 648 Case 751G	$R_{ hetaJA}$	137 72 80	°C/W
Thermal Resistance, Junction-to-Case Case 626 Case 648 Case 751G	R _{θJC}	23 10 12	°C/W

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

1. Either or both input voltages should not exceed the magnitude of V_{CC} or V_{EE}.

2. Power dissipation must be considered to ensure maximum junction temperature (T_J) is not exceeded.

DC ELECTRICAL CHARACTERISTICS (V_{CC} = +15 V, V_{EE} = -15 V, R_L connected to ground, T_A = -40° to +125°C.)

Characteristics	Symbol	Min	Тур	Max	Unit
Input Offset Voltage (V _{CM} = 0)	V _{IO}				mV
$T_A = +25^{\circ}C$			1.0	15 20	
T _A , T _{low} to T _{high}	A)/ /AT		-		1//00
Average Temperature Coefficient of Offset Voltage	$\Delta V_{IO}/\Delta T$	_	20	-	μV/°C
Input Bias Current (V _{CM} = 0)	I _{IB}	-	100	500	nA
Input Offset Current (V _{CM} = 0)	I _{IO}	_	10	50	nA
Large Signal Voltage Gain $V_0 = \pm 10 \text{ V}, R_L = 2.0 \text{ k}$	A _{VOL}	30	100	-	V/mV
Output Voltage Swing ($I_L = 100 \text{ mA}$) $T_A = +25^{\circ}\text{C}$ $T_A = T_{low} \text{ to } T_{high}$ $T_A = +25^{\circ}\text{C}$	V _{OH}	14.0 13.9 –	14.2 - -14.2	- - -14.0	V
$T_A = T_{low}$ to T_{high}	OL.	_	_	-13.9	
Output Voltage Swing ($I_L = 1.0 \text{ A}$) $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25^{\circ}\text{C}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = T_{low} \text{ to } T_{high}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25^{\circ}\text{C}$ $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = T_{low} \text{ to } T_{high}$	V _{OH}	22.5 22.5 - -	22.7 - 1.3 -	- 1.5 1.6	>
Input Common Mode Voltage Range $T_A = +25^{\circ}C$ $T_A = T_{low}$ to T_{high}	V _{ICR}		to (V _{CC} -	,	V
Common Mode Rejection Ratio (R _S = 10 k)	CMRR	70	90	-	dB
Power Supply Rejection Ratio (R _S = 100 Ω)	PSRR	70	90	-	dB
Power Supply Current $T_{A} = +25^{\circ}C \qquad TCA0372$ $TCA0372B$ $T_{A} = T_{low} \text{ to } T_{high} \qquad TCA0372$ $TCA0372B$	I _D	- - -	5.0 8.0 - -	10 10 14 14	mA

$\textbf{AC ELECTRICAL CHARACTERISTICS} \ (V_{CC} = +15 \ V, \ V_{EE} = -15 \ V, \ R_L \ connected \ to \ ground, \ T_A = +25 ^{\circ}C, \ unless \ otherwise \ noted.)$

Characteristics	Symbol	Min	Тур	Max	Unit
Slew Rate (V_{in} = -10 V to +10 V, R_L = 2.0 k, C_L = 100 pF) A_V = -1.0, T_A = T_{low} to T_{high}	SR	1.0	1.4	-	V/μs
Gain Bandwidth Product (f = 100 kHz, C_L = 100 pF, R_L = 2.0 k) T_A = 25°C T_A = T_{low} to T_{high}	GBW	0.9 0.7	1.4 -	1 1	MHz
Phase Margin $T_J = T_{low}$ to T_{high} $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$	Фm	-	65	-	Degrees
Gain Margin $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$	A _m	-	15	-	dB
Equivalent Input Noise Voltage $R_S = 100 \Omega$, $f = 1.0 to 100 kHz$	e _n	-	22	-	nV/√Hz
Total Harmonic Distortion $A_V = -1.0$, $R_L = 50 \Omega$, $V_O = 0.5$ VRMS, $f = 1.0$ kHz	THD	_	0.02	_	%

NOTE: In case V_{EE} is disconnected before V_{CC} , a diode between V_{EE} and Ground is recommended to avoid damaging the device.

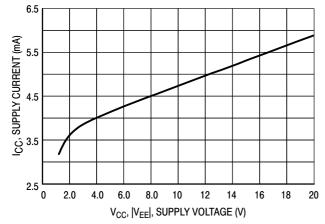


Figure 2. Supply Current versus Supply Voltage with No Load

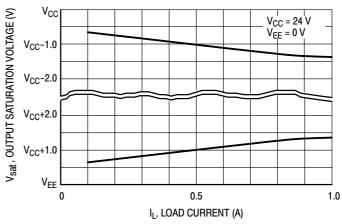


Figure 3. Output Saturation Voltage versus Load Current

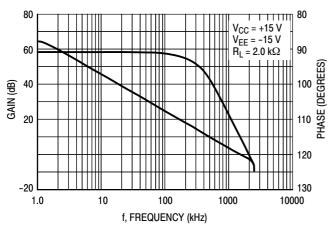


Figure 4. Voltage Gain and Phase versus Frequency

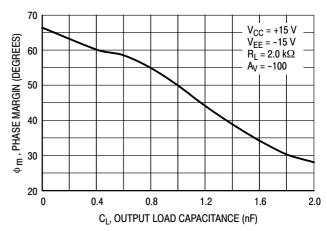


Figure 5. Phase Margin versus Output Load Capacitance

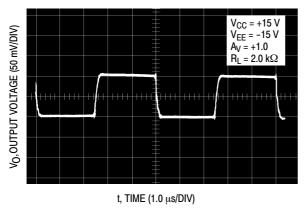


Figure 6. Small Signal Transient Response

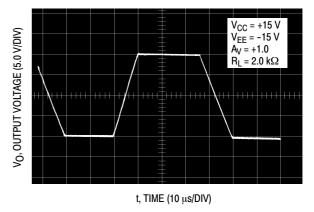


Figure 7. Large Signal Transient Response

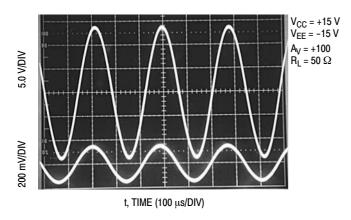


Figure 8. Sine Wave Response

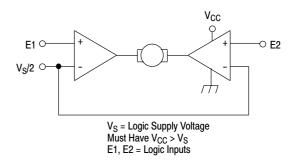
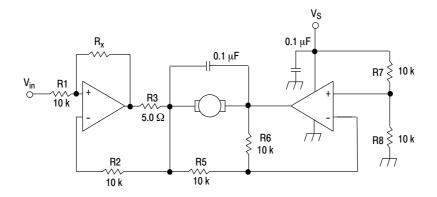


Figure 9. Bidirectional DC Motor Control with Microprocessor-Compatible Inputs



For circuit stability, ensure that $R_X > \frac{2R3 \cdot R1}{R_M}$ where, R_M = internal resistance of motor. The voltage available at the terminals of the motor is: $V_M = 2 (V_1 - \frac{V_S}{2}) + |R_0| \cdot I_M$ where, $|R_0| = \frac{2R3 \cdot R1}{R_X}$ and I_M is the motor current.

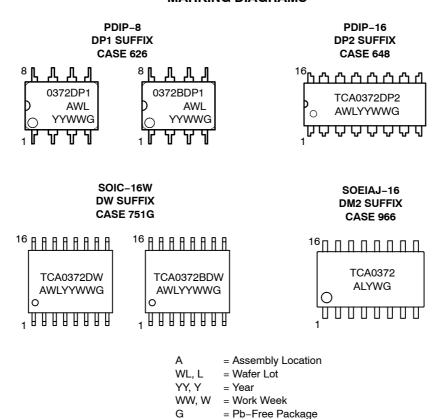
Figure 10. Bidirectional Speed Control of DC Motors

ORDERING INFORMATION

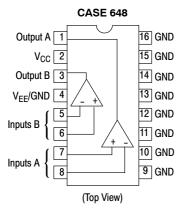
Device	Package	Shipping [†]
TCA0372DWG	SOIC-16W (Pb-Free)	47 Units / Rail
TCA0372DWR2G	SOIC-16W (Pb-Free)	1000 Tape & Reel
TCA0372BDWR2G	SOIC-16W (Pb-Free)	1000 Tape & Reel
TCA0372DP1G	PDIP-8 (Pb-Free)	50 Units / Rail
TCA0372BDP1G	PDIP-8 (Pb-Free)	50 Units / Rail
TCA0372DP2G	PDIP-16 (Pb-Free)	25 Units / Rail
TCA0372DM2ELG	SOEIAJ-16 (Pb-Free)	2500 Tape & Reel

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

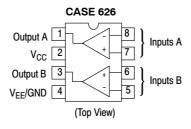
MARKING DIAGRAMS

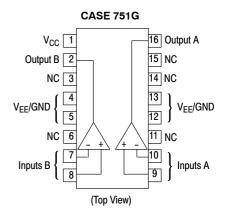


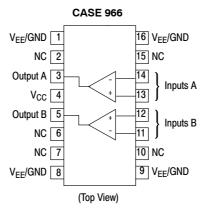
PIN CONNECTIONS



*Pins 4 and 9 to 16 are internally connected.

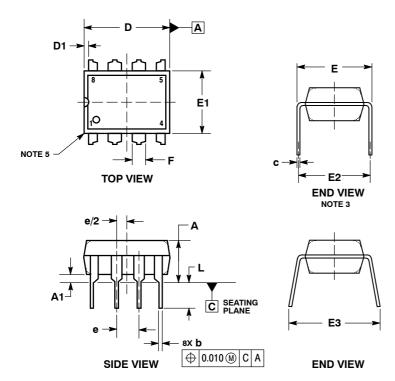






PACKAGE DIMENSIONS

PDIP-8 **DP1 SUFFIX** CASE 626-05 ISSUE M



NOTES:

- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.

 2. CONTROLLING DIMENSION: INCHES.

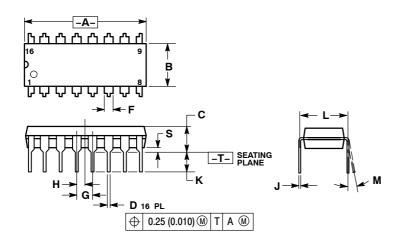
 3. DIMENSION E IS MEASURED WITH THE LEADS RESTRAINED PARALLEL AT WIDTH E2.

 4. DIMENSION E1 DOES NOT INCLUDE MOLD FLASH.

 5. ROUNDED CORNERS OPTIONAL.

	INCHES			MILLIMETERS		
DIM	MIN	NOM	MAX	MIN	NOM	MAX
Α			0.210			5.33
A1	0.015			0.38		
b	0.014	0.018	0.022	0.35	0.46	0.56
С	0.008	0.010	0.014	0.20	0.25	0.36
D	0.355	0.365	0.400	9.02	9.27	10.02
D1	0.005			0.13		
E	0.300	0.310	0.325	7.62	7.87	8.26
E1	0.240	0.250	0.280	6.10	6.35	7.11
E2	0.300 BSC		7.62 BSC)	
E3			0.430			10.92
е	(0.100 BSC		2.54 BSC)
L	0.115	0.130	0.150	2.92	3.30	3.81

PDIP-16 **DP2 SUFFIX** CASE 648-08 **ISSUE T**



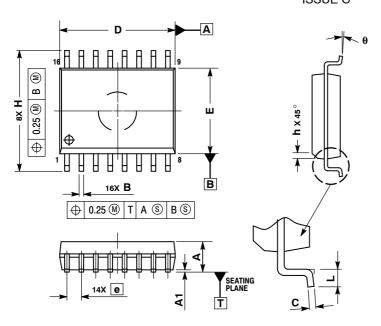
- NOTES:
 1. DIMENSIONING AND TOLERANCING PER
- ANSI Y14.5M, 1982.
 CONTROLLING DIMENSION: INCH.
 DIMENSION L TO CENTER OF LEADS
 WHEN FORMED PARALLEL.
- DIMENSION B DOES NOT INCLUDE
- MOLD FLASH.

 5. ROUNDED CORNERS OPTIONAL.

	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.740	0.770	18.80	19.55
В	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100	BSC	2.54	BSC
Н	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
М	0°	10 °	0 °	10 °
S	0.020	0.040	0.51	1.01

PACKAGE DIMENSIONS

SOIC-16W **DW SUFFIX** CASE 751G-03 **ISSUE C**



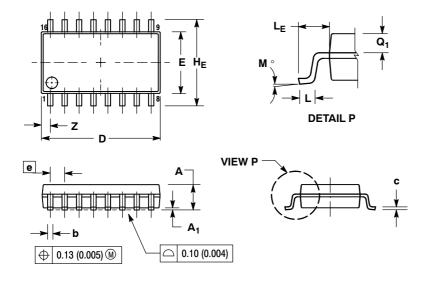
- 1. DIMENSIONS ARE IN MILLIMETERS.
 2. INTERPRET DIMENSIONS AND TOLERANCES
- PER ASME Y14.5M, 1994.
 3. DIMENSIONS D AND E DO NOT INLCUDE MOLD
- PROTRUSION.

 MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.

 DIMENSION B DOES NOT INCLUDE DAMBAR
 PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS
 OF THE B DIMENSION AT MAXIMUM MATERIAL

	MILLIMETERS			
DIM	MIN MAX			
Α	2.35	2.65		
A1	0.10	0.25		
В	0.35	0.49		
С	0.23	0.32		
D	10.15	10.45		
E	7.40	7.60		
е	1.27	BSC		
Н	10.05	10.55		
h	0.25	0.75		
L	0.50	0.90		
A	0 0	70		

SOEIAJ-16 **DM2 SUFFIX** CASE 966 **ISSUE A**



NOTES:

- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

 2. CONTROLLING DIMENSION: MILLIMETER.

 3. DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS AND ARE MEASURED AT THE PARTING LINE. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.15 (0.006) DED RISE. PER SIDE.

 4. TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.

 5. THE LEAD WIDTH DIMENSION (b) DOES NOT
- INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 (0.003)
 TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSIONS AND ADJACENT LEAD TO BE 0.46 (0.018).

	,	,		
	MILLIMETERS		INC	HES
DIM	MIN	MAX	MIN	MAX
Α		2.05		0.081
A ₁	0.05	0.20	0.002	0.008
b	0.35	0.50	0.014	0.020
C	0.10	0.20	0.007	0.011
D	9.90	10.50	0.390	0.413
Ε	5.10	5.45	0.201	0.215
е	1.27	BSC	0.050	BSC
HE	7.40	8.20	0.291	0.323
L	0.50	0.85	0.020	0.033
LE	1.10	1.50	0.043	0.059
M	0 °	10 °	0 °	10 °
Q_1	0.70	0.90	0.028	0.035
Z		0.78		0.031

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